

FIG. 1

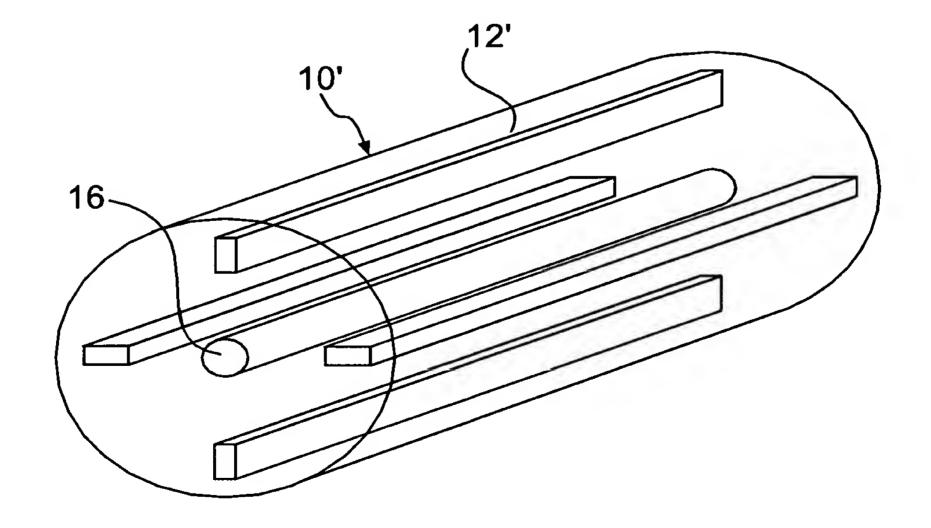


FIG. 2

The grap days have days to the state of the

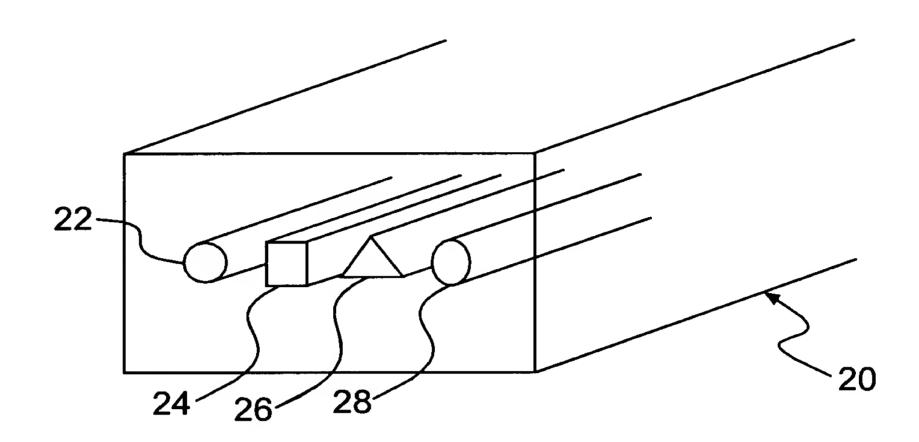
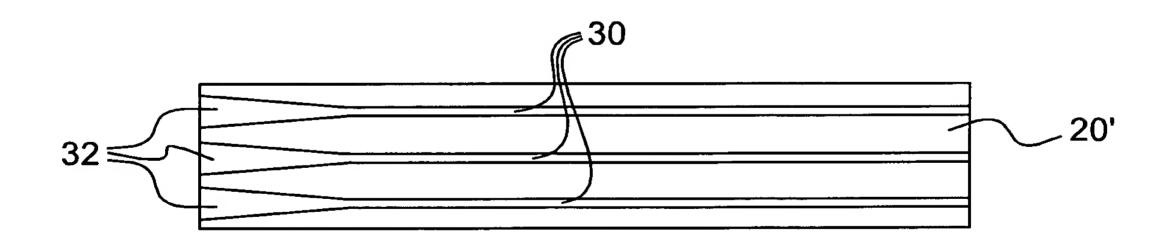


FIG. 3a



The first state first state from the state with the first state of the state state of the state

FIG. 3b

The perpendicular perpendicular control of the second control of t



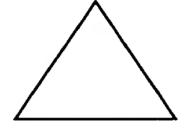


FIG. 4c

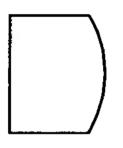


FIG. 4e

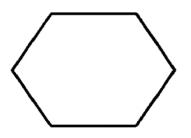


FIG. 4g

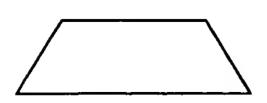


FIG. 4i

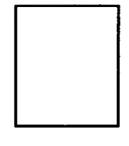


FIG. 4b

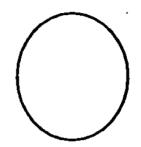


FIG. 4d

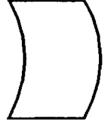


FIG. 4f



FIG. 4h

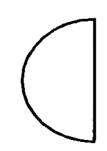


FIG. 4j

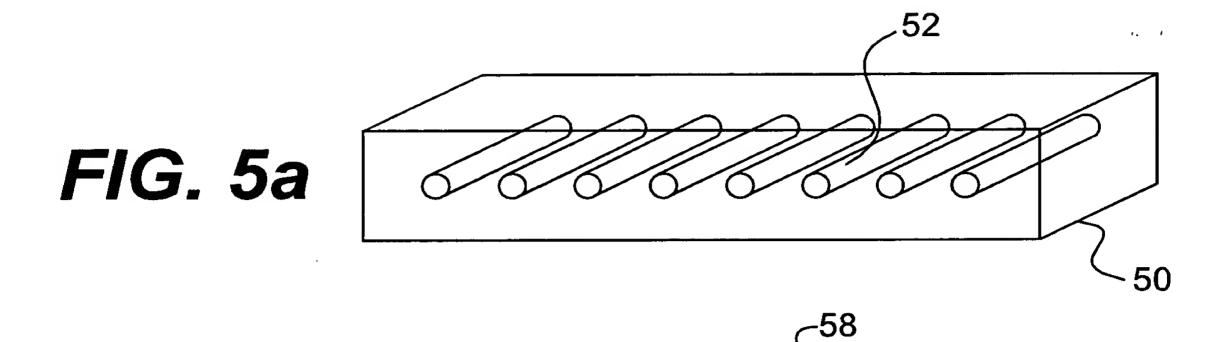


FIG. 5b

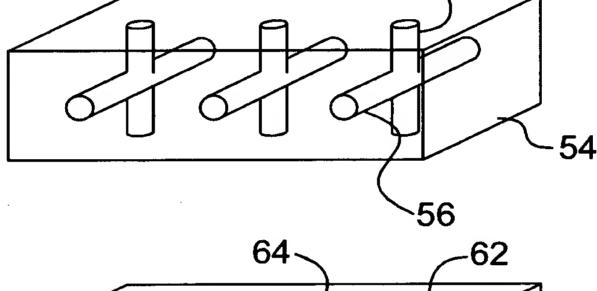


FIG. 5c

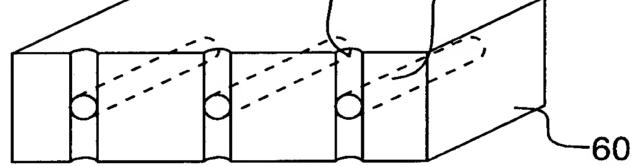


FIG. 5d

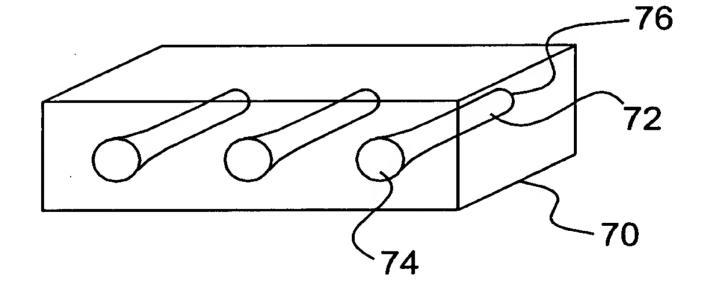
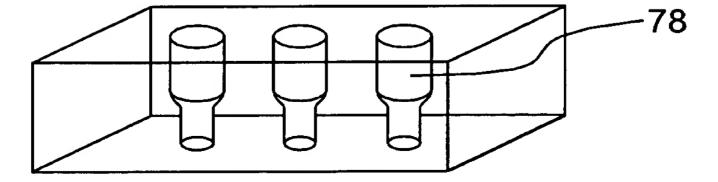
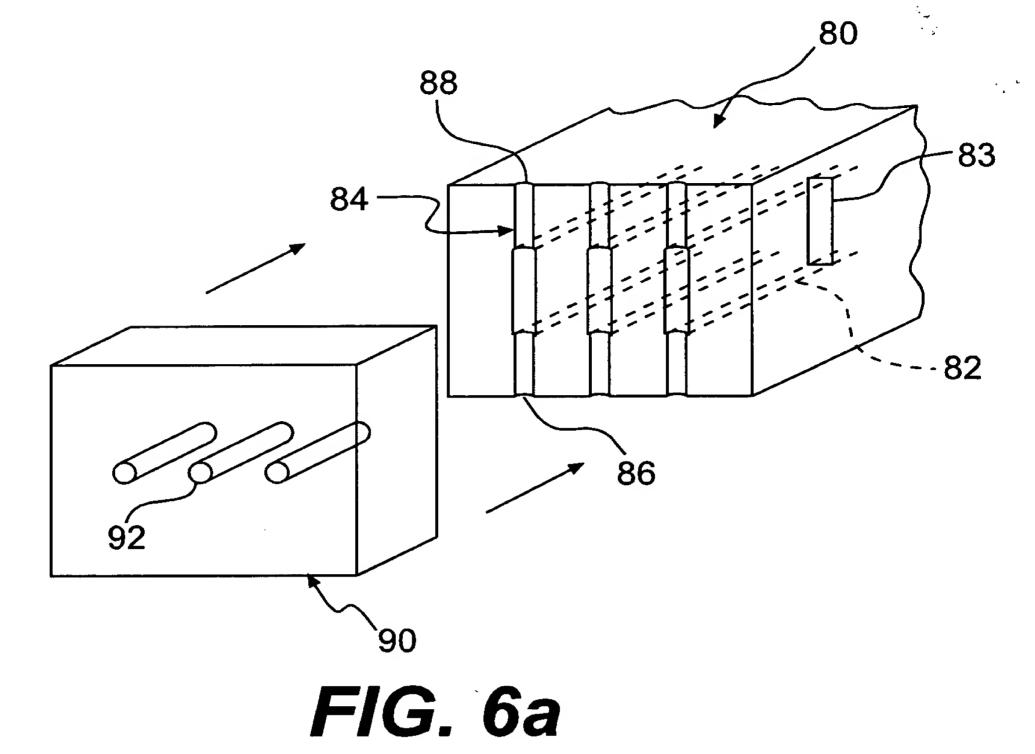


FIG. 5e



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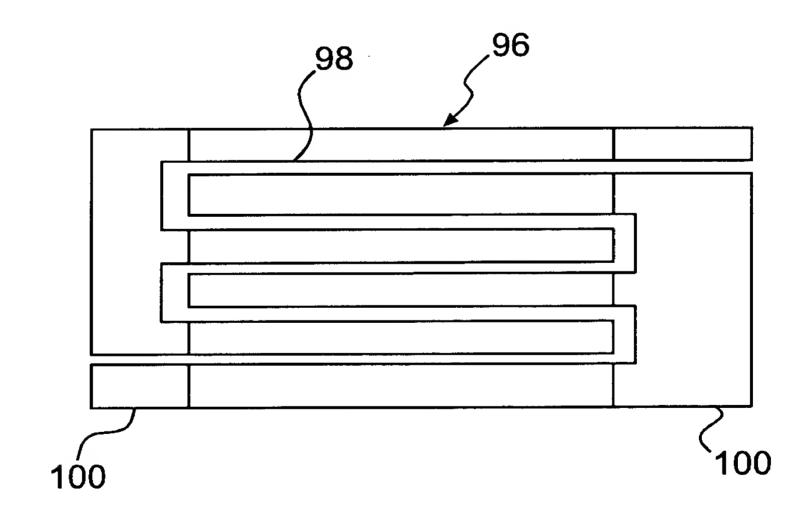
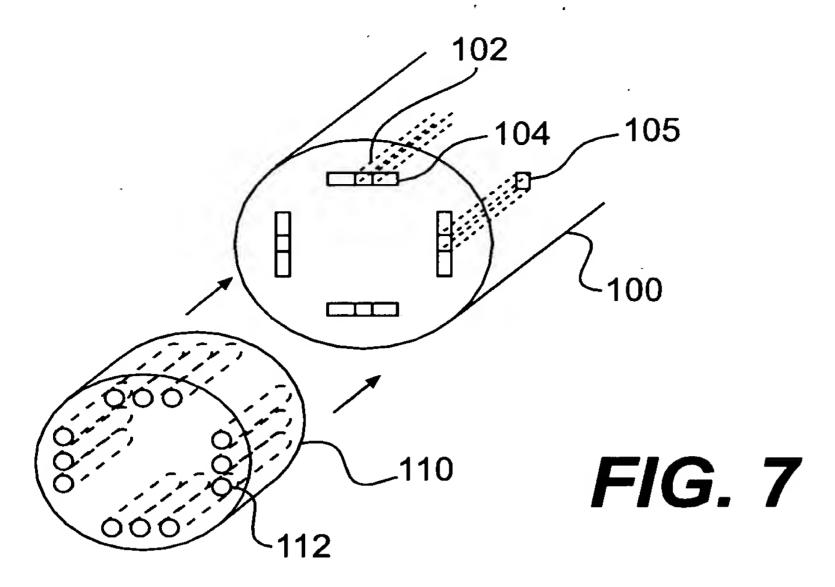


FIG. 6b

The first time for the first first time that and one in the first first time that



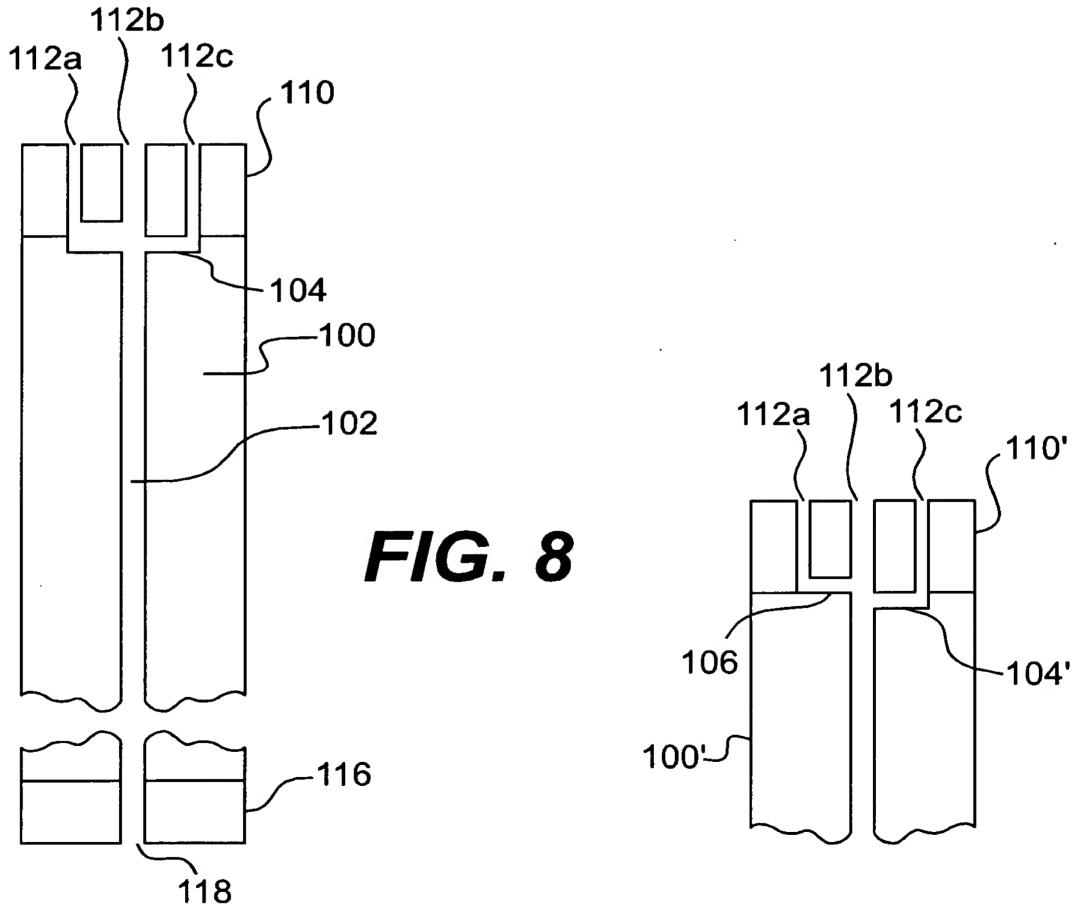


FIG. 9

The factor and but may be a the third and and the flow the factor of the

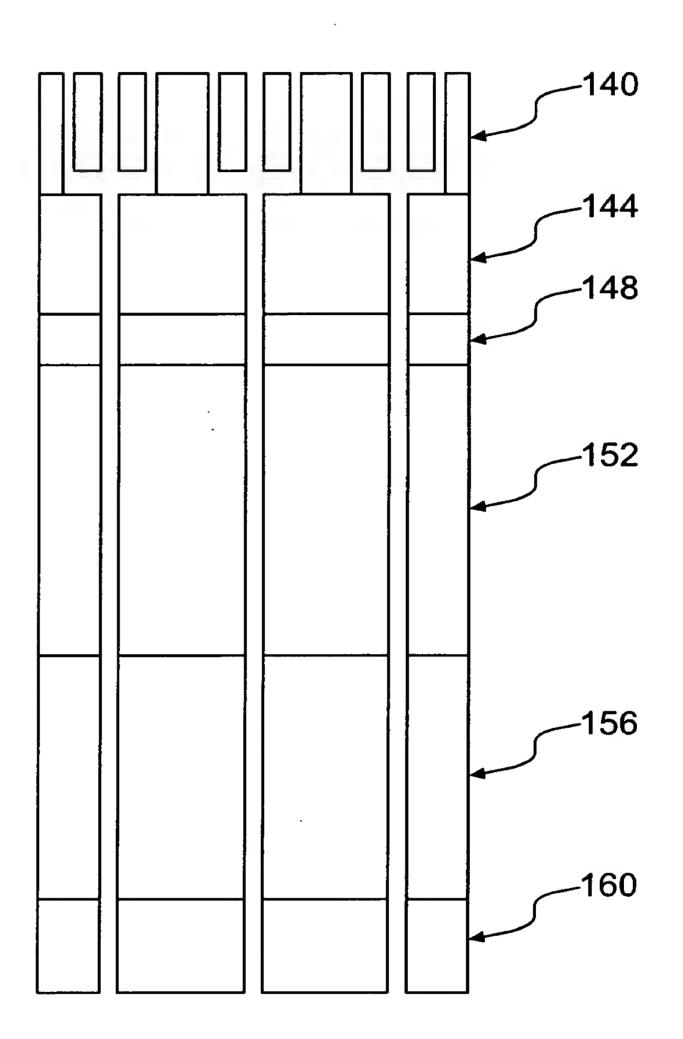


FIG. 10

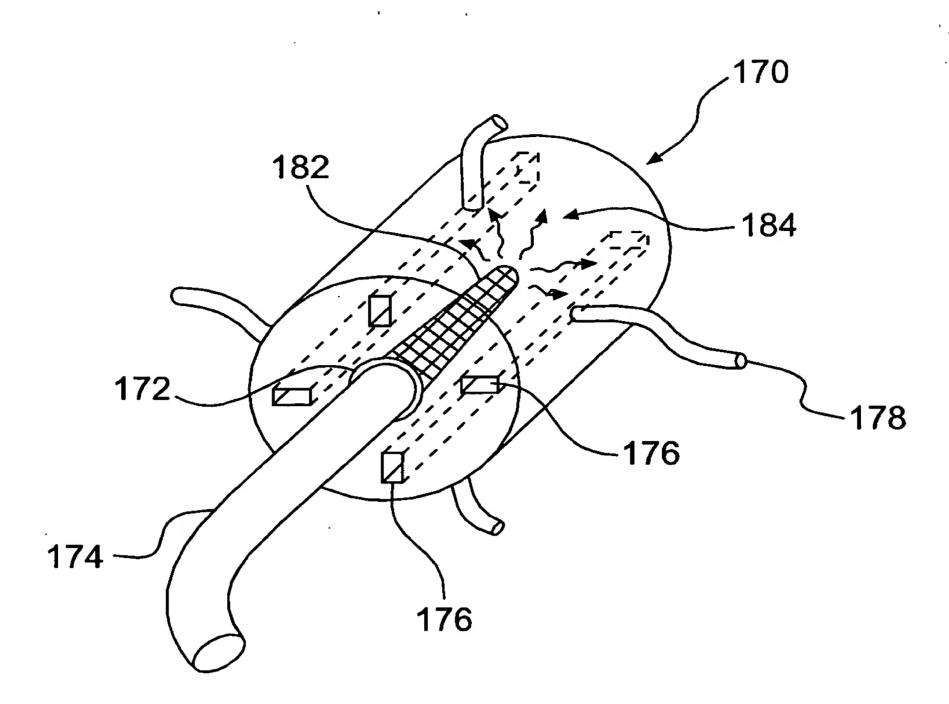


FIG. 11

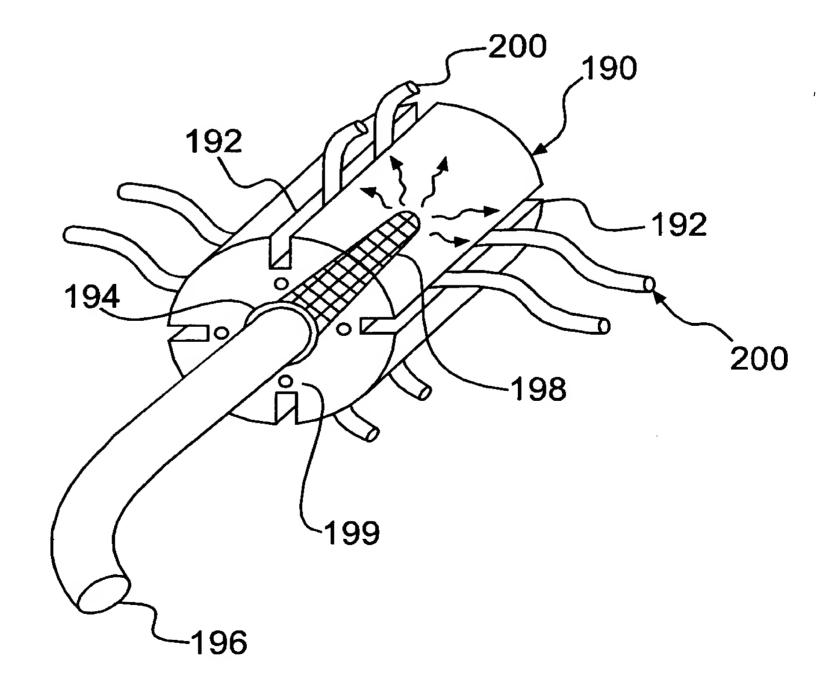
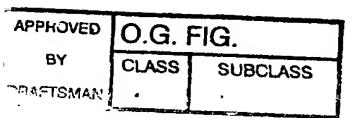


FIG. 12

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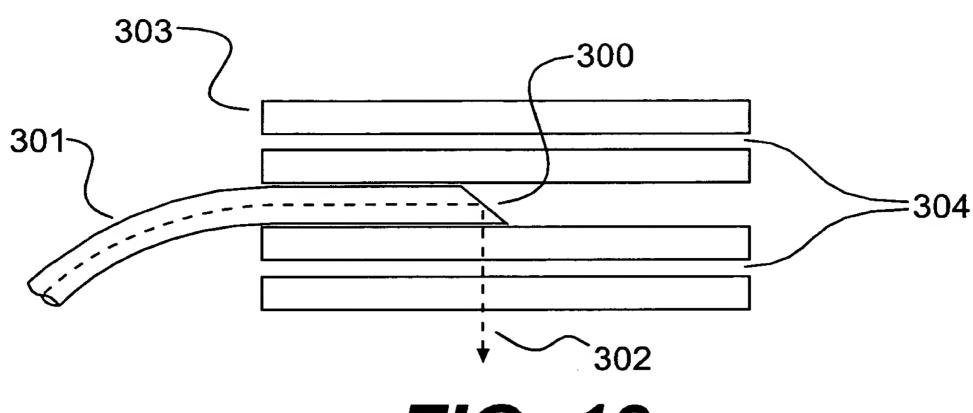
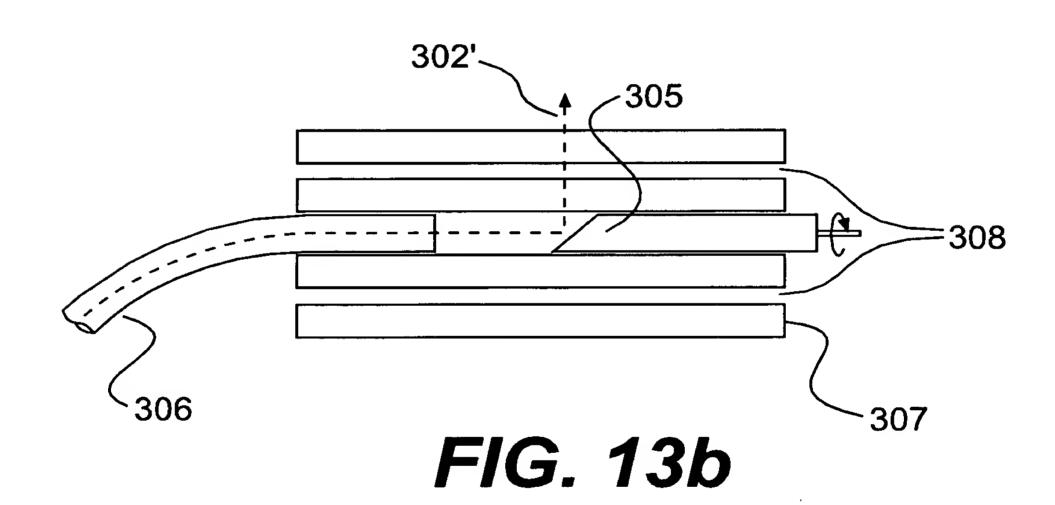


FIG. 13a



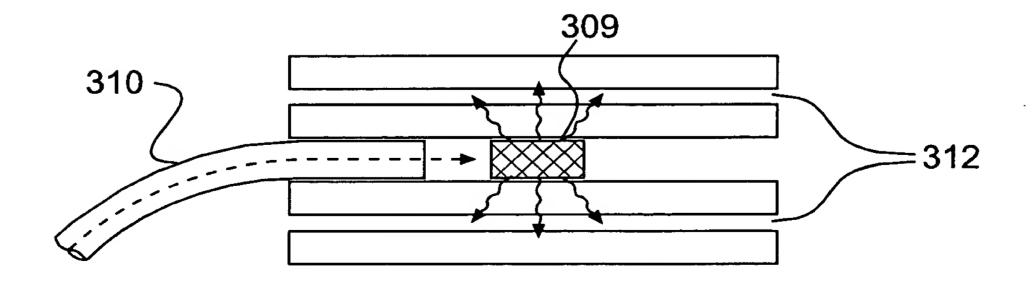


FIG. 13c

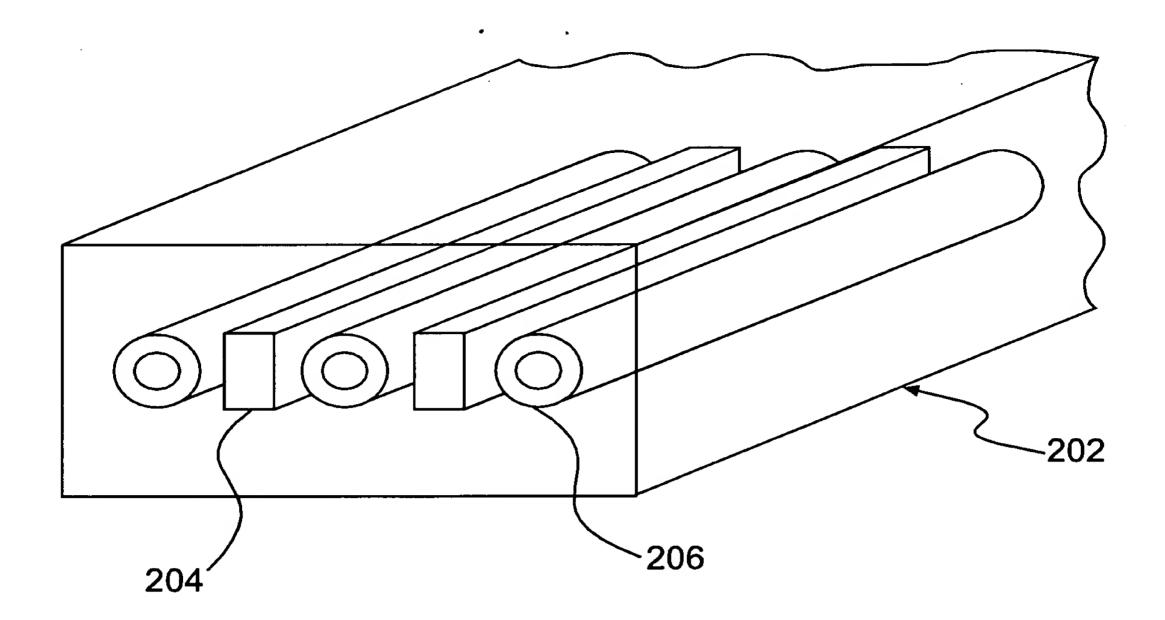


FIG. 14

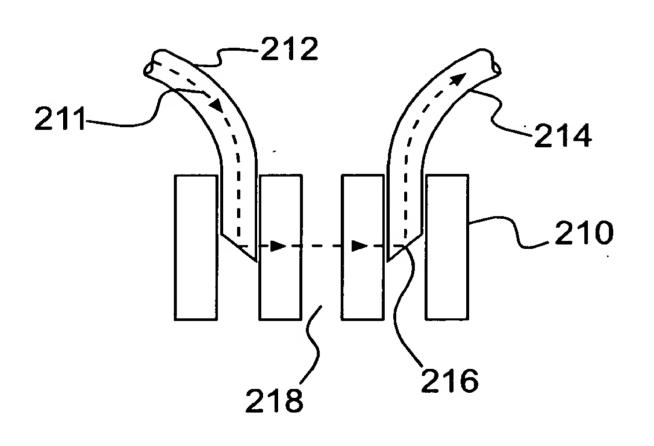


FIG. 15a

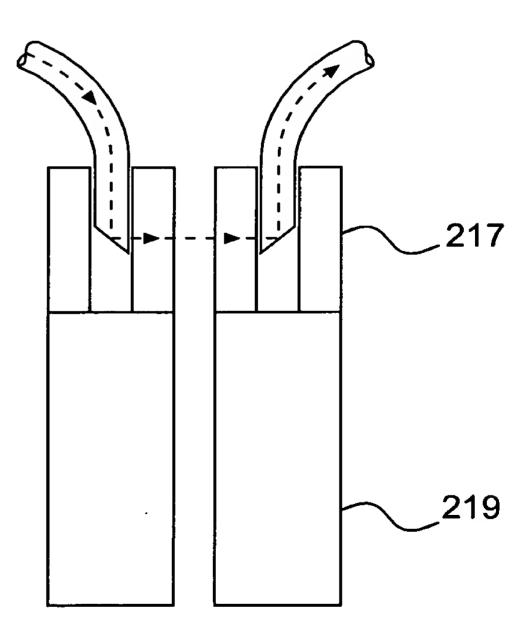


FIG. 15b

The first that the tend that the three that the three the true that the

The first start for the first start start

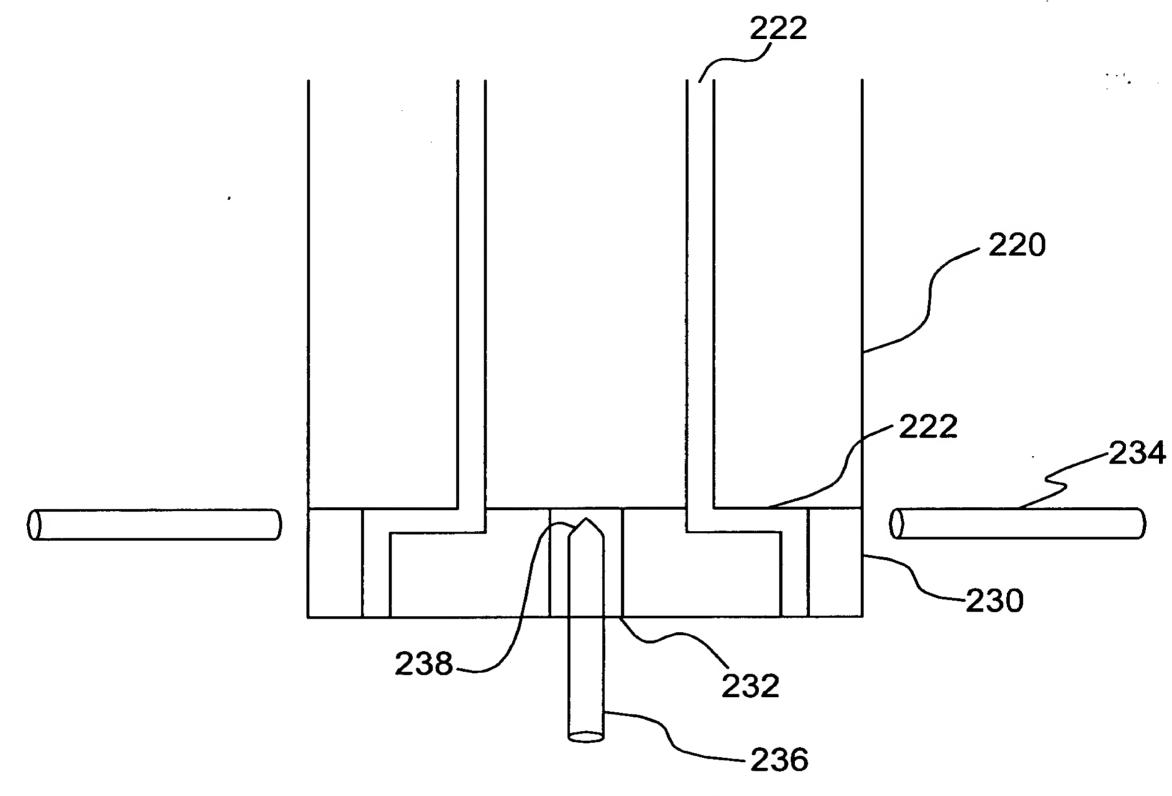
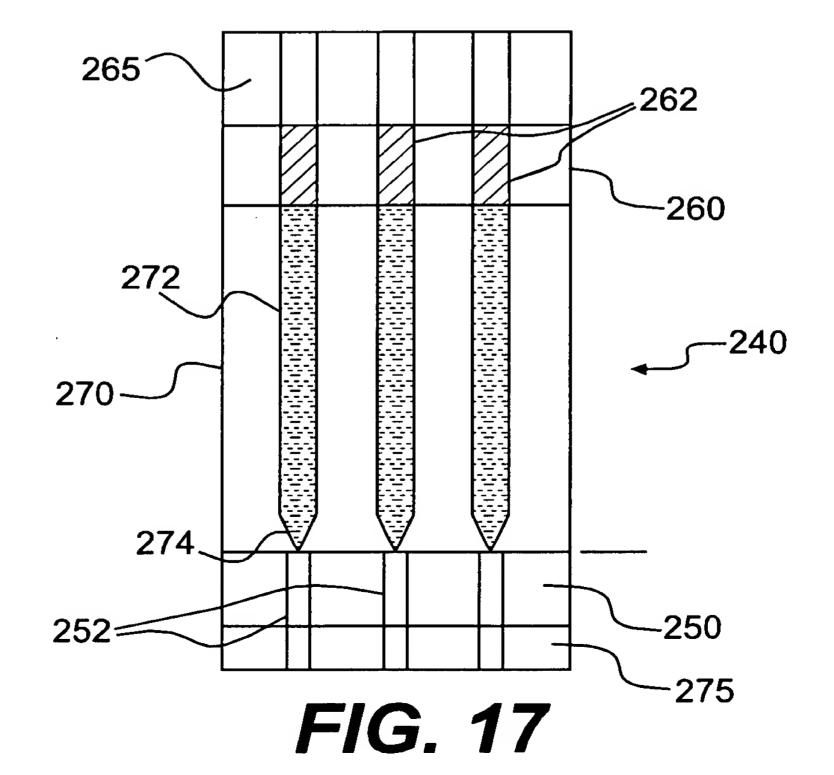
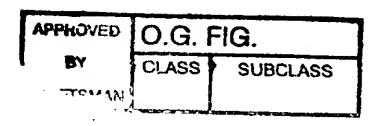


FIG. 16





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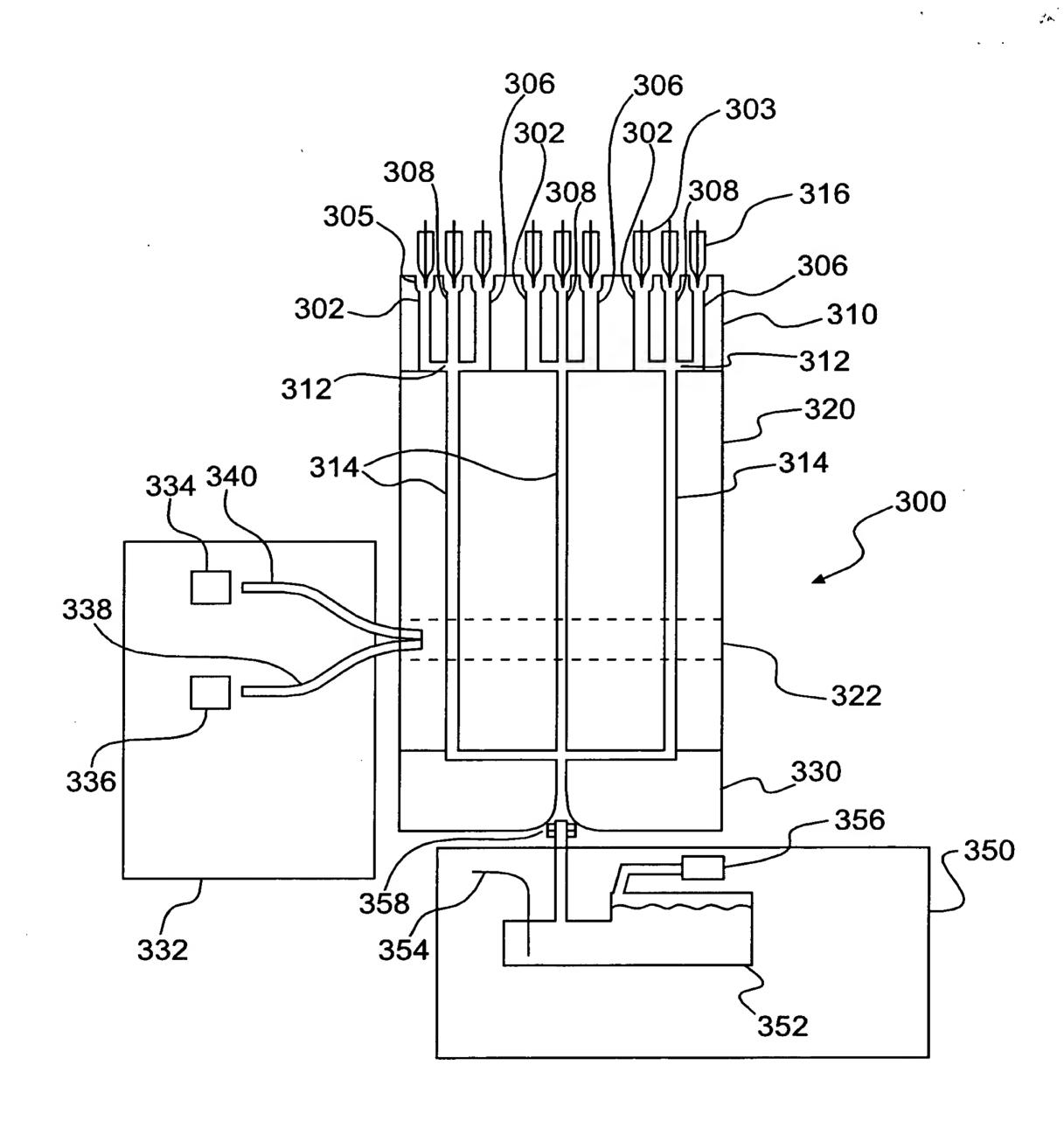


FIG. 18

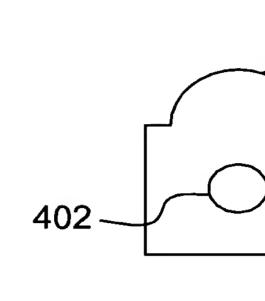


FIG. 19a

400

404

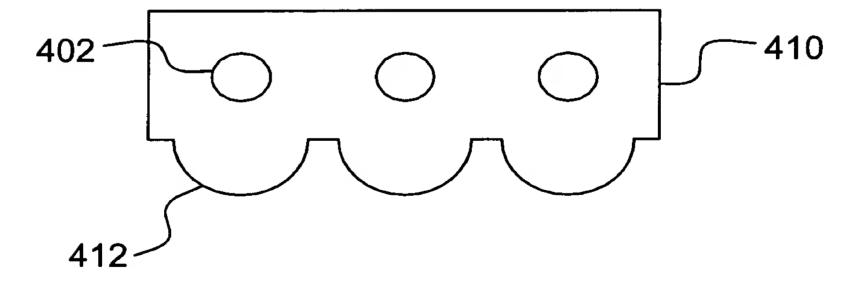


FIG. 19b